Radu-Alexandru MANTU

(+40) 729 589 162 andru.mantu@gmail.com github.com/RaduMantu 259 Gheorghe Ionescu Sisesti, Ap. 1 Bucharest, Romania

EDUCATION

Faculty of Automatic Control and Computer Science, Polytechnic University of Bucharest,

Doctorate in Network Security
2020-2025

Thesis: Enhancing application awareness through distributed firewalling

Master of Advanced Security Systems
2018-2020

Thesis: Electromagnetic Analysis of Computational Systems

Bachelor of Computer Science 2014-2018

Thesis: Control Flow Integrity based on Controlled Channel

"George Cosbuc" Bilingual National College

High School Diploma
2010-2014

Degree in mathematics-informatics and a bilingual specialization, with focus on English.

WORK EXPERIENCE

SANCTUARY Systems GmbH. – software engineer

2023-present

Continued the work started at TU Darmstadt. Additionally implemented an RPC mechanism based on Capnp and running over a CanBus | ISO-TP | TLS secure channel for communicating with a Hardware Security Module. Also implemented a number of protocol-specific scanners for OT networks.

Technical University of Darmstadt – research assistant

2022

Helped develop and port a secure platform consisting of an ARM hypervisor and secure OS from FVP to actual hardware (i.MX8M platforms).

Polytechnic University of Bucharest – research assistant

2020-presen

Conducted research regarding computer network firewalling technologies. Founded and organized three editions of the ARM Summer School, sponsored by Google and NXP.

National University of Singapore – research intern

2020

"Refined Grey-Box Fuzzing with SIVO" - DIMVA2021

Helped develop core components of SIVO, a state-of-the-art fuzzer. My primary responsibility was creating a testing environment for comparing SIVO to 11 other widely recognized fuzzers on a wide range of benchmark programs. Currently working on integrating it into Google FuzzBench.

Polytechnic University of Bucharest – student research assistant

2017-2020

"Control Flow Integrity Based on Controlled Channel" - CSCS2019

Developed a Linux Kernel hack that allows tracing the memory accesses of a pool of processes, based on page table invalidation. Utilizing the logs generated as a result of a training process, we constructed a Control Flow Graph, used to ensure Control Flow Integrity.

Romanian Foreign Intelligence Service – intern

2018

One month course in Cryptology under the tutelage of domain experts. Studied classical ciphers, stream and block ciphers, steganography and related mathematics.

• Fitbit - software engineer intern

2018

Developed a proxy web service based on Spring API between HTML and Apache Thrift. My main contributions to the project consisted of implementing a JAR introspection system used to automatically translate the classes that implement the Thrift client interfaces to a GraphQL schema and a method of modifying the class loader hierarchy at runtime to provide additional isolation to the loaded client stubs.

Teaching assistant
2018-present

Taught 1st year *Introduction to Informatics* and *Assembly Language*, 2nd year *Communication Protocols*, 4th year *Performance Evaluation* and *Introduction to Computer Security* labs to Computer Science students. Contributed with laboratory material and assignment grading. Acted as BitDefender ambassador for the Performance Evaluation team since February 2019 and until March 2021.

Unikraft Summer of Code - Unikraft

2021

Attended a two week online workshop on Unikraft, a unikernel generation framework. Learned basic usage, application/library porting, debugging and gained insight into internal systems (e.g.: syscall shim). Also participated in the final hackathon where my team placed first.

Security Summer School at University of Padua

2019

Attended talks at this week-long summer school. Presented work on controlled channels.

Innovation Labs Mentorship Programme – ROS

2019

Programmed an autonomous floor sweeper starting from a manually operated one that our team modified. Using ROS, a human operator would guide the robot in order to create a map of the floor using its lidar sensor. Then, the robot would create an optimal route for traversing the entire surface and dynamically update its plan if it encountered any obstacles. This project has been put on hold while we refocus on another task with a better defined team.

Palo Alto CTF 2019

Participated in the Palo Alto Networks Cybersecurity Academy CTF.

NXP Linux Embedded Challenge - OpenGL and UDOO Neo

2017

Programmed a robot to acquire data using a lidar while moving. The data was processed and sent to a server that inserted individual entries or deleted regions from a quad tree, ran a clustering algorithm on the known vertices and displayed the map of the explored area with each identified object colored differently.

GameCup first edition – OpenGL and Unity

2017

Reached the final stage of the competition with a gravity themed 3D puzzle game developed in Unity.

- Innovation Labs Mentorship Programme Neural Networks, Android Development, Databases (2017) Helped build a neural network that, based on the shipments and sales history of a shop, predicts within a reasonable margin of error the probability that expired goods exist on display and the affected quantity. Created a database generator for training and testing the neural network.
- NLP legal application research Python and Stanford Parser

2014-2016

Used Stanford Parser to determine the definition of terms in legal contracts. The terms were obtained through a probabilistic heuristic. The definitions were extracted from recurring structures observed in the parse trees

Maze Solving Robot - Arduino and OpenGL

Ranked 2nd at InfoEducatie, national stage. The robot traversed a maze and sent data to a computer that generated a 3D map with different height levels.

Database Management System - Visual C# and SQL

2012

For InfoEducatie contest, national stage. Software allowed database manipulation for retail clerks based on authorization level.

LANGUAGES

- English Cambridge English: Advanced (CAE)
- German Goethe-Zertifikat: A2